

# Shibaura Machine

View the Future with You

#### **ISO 9001**



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\* We reserve the right to change any of specifications in this catalog without notice in order to effect improvements.

# Shibaura Machine

# MP-2620(U)

**Double Column Machining Center Bridge type Multi-Purpose Machine** 



# SHIBAURA MACHINE'S ADVANCED TECHNOLOGIE have been focused on our bridge type multi-purpose machine.

# MP-2620(U)

MP-2620(U) capable of handling multiple processed.

Machining center, vertical turning center, and as a 5 axis machine when selecting the optional spindle head.

The overall design of this machine is an integral feature to also process an extensive range of

MP-2620(U) contributes to minimize lead time in production by integrating several processes in one machine.

All linear axise X, Y and Z are designed with twin drive mechanism in order to achieve high rigidity and high accuracy.

This attribute allows swift machine motion even at 40m/min in rapid and 20m/min in cutting feed mode.

MP-2620(U) has a contouring C-axis and NC COTROLLED TURNING TABLE. Additionally AN OPTIONAL 4-axis head for 5-axis machining.

MP-2620(U) "TOSNUC PX100" our stateof-the-art controller which is an integrated system of our TOSNUC999 and PC-HMI developed by Shibaura Machine.

MP-2620(U) Is a Multi-purpose machine designed to execute various function in diverse machining application and processes, combined with several attachments as if it were a machining center and a turning center. **Turning operation** 

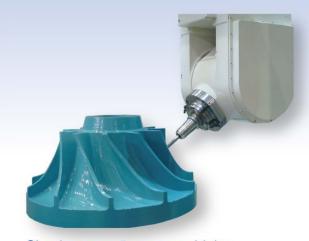




### **Milling operation**



inclined drilling with optional 4-axis head



Simultaneous 5 axes machining

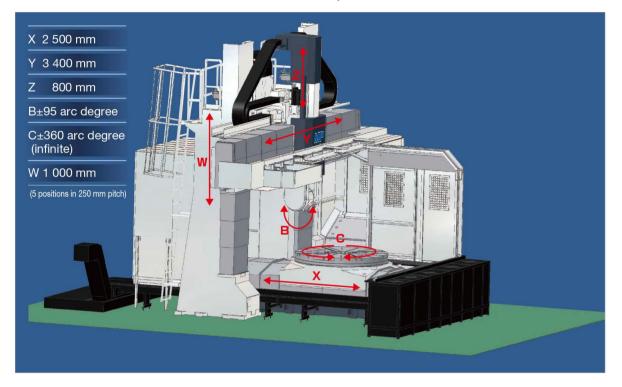


# **Axis configuration**

The standard machine has 4 axes which consist of three (3) linear axes of X, Y, and Z, and one (1) rotary axis C.

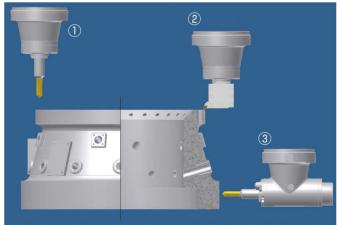
A 4-axis head in an (optional accessory) for 5-axis machining.

The W axis is a crossrail that can be located at 5 positions is 250mm increments.



# Productivity

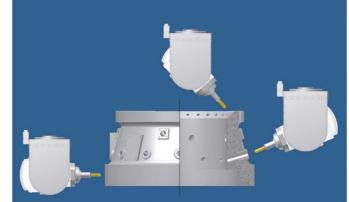
Several kinds of attachments make the machine a multi-purpose machine.



The Snout 240 can be used for boring and turning operation as shown in figure 1, and 2.

The angle head can be utilized for machining the side of a workpiece as shown in figure 3.

4-axis head is shown for machining on any inclined surface.



# **Accessibility**



#### Chip cover with ceiling

The chip cover with ceiling enclosure is standard accessory, and the L-shape door with ceiling compliment an ergonomic design, enabling easy access to the area around the table.

Axcellent chip discharge around a wide enclosure.

Wide space and easy chip discharge around the table

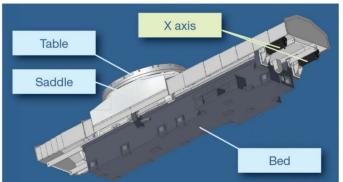
A round rigid table is utilized turning and milling operations for both turning and milling operations.



# Swift motion, high rigidity, high accuracy

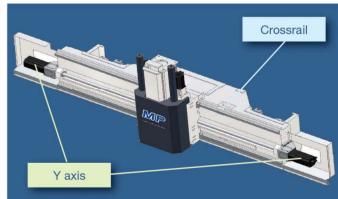
The twin drive mechanisms on all linear axes assure swift motion, high rigidity, and higher accuracy on the machine.

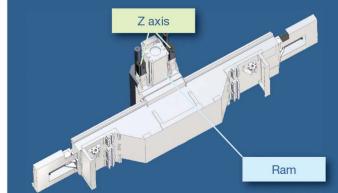
Solid casted brackets support ball screws on all linear axes to assure high positioning accuracy.





Solid casted brackets

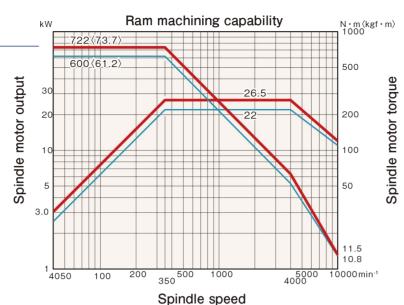




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# **Milling capability**



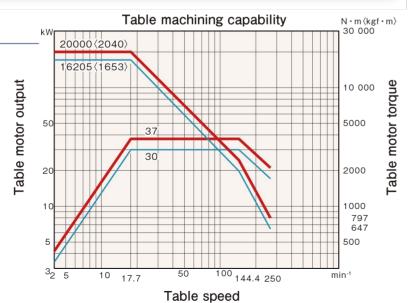


Material: \$55C (machined with the "Snout 240")

Drilling Face milling End milling Tool diameter | Surface speed | Spindle speed Feedrate Machining width Cutting depth Machined volume Ram extension mm/min cm<sup>3</sup>/min 175 350 910 120 764 400 Face milling 120 600 440 30 660 400 End milling  $\phi$ 63 50 Drilling 22 100 50  $\phi$ 69.5 350

# **Turning capability**

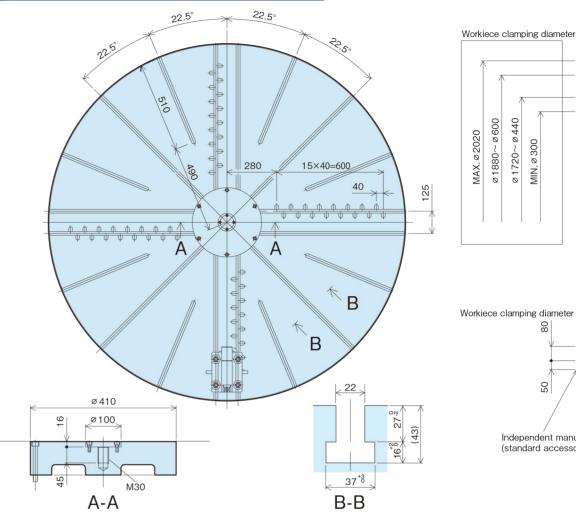


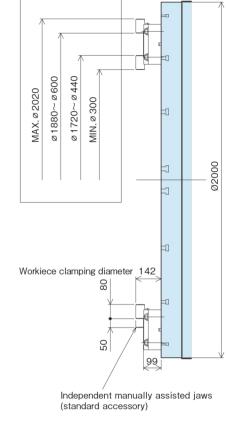


Material: \$\$400 (machined with the "Snout 240")

	Table speed min <sup>-1</sup>	Federate mm/rev	Cutting depth mm	Ram extension mm	Machining diameter mm	Load ratio %
Machining outside	25	1	7.5	800	900	50
Machining top surface	25	1	7.5	650	-	37

# **Table configuration**

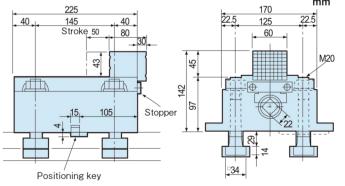




# **Manually assisted** independent jaws (4 sets)

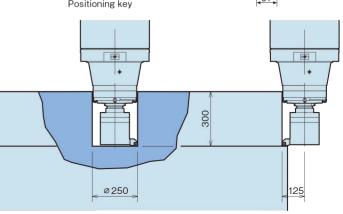
· Maximum clamping force : 4 tons, (18kgf-m clamping torque)

· Mass of a unit; 28 kg



### **■**Cautions on turning operation

Turning depth on a square type tool holder some restrictions "on a case-by case basis" please consult us for further detail.



# **Machine Specifications**

	Machine Specifications		unit	MP-2620 (U)
	X-axis travel(table longitudinal direction	n)	mm[in]	2 500 [98.4]
Travel	Y-axis travel(spindle head crosswise direct	tion)	mm[in]	3 400 [133.8]
	Z-axis travel(ram vertical direction)		mm[in]	800 [31.4]
	W-axis travel(crossrail elevation)		mm[in]	1 000 [39.3] ( 9.8×5steps)
	C-axis travel(table rotation)		deg	±360 (infinite)
	Height(distance from table top face to gage plane of	Snout 240)	mm[in]	1 750 [70.2]
	Distance between column		mm[in]	2 600 [102.3]
	Table diameter		mm[in]	2 000 [78.7]
	Maximum mass on table		kg[lbs]	10 000 [22 000]
Toble	Table speed		min <sup>-1</sup>	2 ~ 250
Table	Number of speed range			2 ranges
	Maximum torque		N.m[Ft-lbs]	20 000 [14 802]
	Table drive motor		kw[hp]	AC37/30 [AC50/40] (30 min continous rating)
	Spindle speed		min <sup>-1</sup>	40 ~ 10 000
	Number of speed range			2 ranges
	Taper on the spindle			7/24 taper No.50 (BIG PLUS)
Colodla	Maximum torque		N.m[Ft-lbs]	722.7 [534.8]
Spindle	Bore of main bearing	mm[in]	100 [3.9]	
	Guide for ram			Rolling guide
	Ram sectional dimensions		mm[in]	380×380 [14.9×14.9]
	Spindle drive motor		kw[hp]	AC26.5/22 [AC35/30] (30 min continous rating)
		X/Y	mm/min[ipm]	40 000 [1 574] (Lard on table must be less than 3000 kg)
	Rapid travers rate	Z	mm/min[ipm]	40 000 [1 574] (standard snout)
Coodyoto				30 000 [1 181] (except standard snout)
Feedrate		С	deg/min	1 080(3 min <sup>-1</sup> )
	Feedrate for machining	X/Y/Z	mm/min[ipm]	1 - 20 000 [0.04 - 787]
	reediate for machining	С	deg/min	1 - 1 080(3 min <sup>-1</sup> )
	Tool shank			MAS BT50
Tool	Pull stud		MAS P50T-1(45°)	
	Tool storage capacity			60 tools
Machina	Machine height		mm[in]	6 600 [260]
Machine	Floor space		mm[in]	7 515×8 705 [335×394]
size	Mass of machine		kg[lbs]	55 000 [121 000]
	Positioning accuracy	X/Y/Z	mm[in]	±0.007/1 000 [±0.0002/39.4]
A courses.	FOSITIONING ACCURACY	Positioning accuracy C		±5
Accuracy	Repeatability X/Y/Z		mm[in]	±0.003 [±0.00012]
	переатаршту	С	sec	±3

# **Standard accessories**

- Snout 240
- Automatic attachment indexing device (AAI)
- · · · 4 positions every 90 degrees
- Automatic tool clamp/unclamp device
- Automatic tool changer (ATC) Tool storage capacity : 60 tools.
- Spindle shape for BIG PLUS type shank
- Scale feedback on X, Y, Z, and C axis (hybrid feedback)
- Hvdraulic unit
- Spindle head cooling unit
- Telescopic steel cover for bed
- Telescopic steel cover for crossrail
- Telescopic steel cover for column
- Installation parts (leveling block type)

- Special maintenance tool set
- Independent manually-operated jaws (4 units)
- Coolant through spindle

Available on "snout 240", and refer to other attachment in detail.

- Operation panel on stand
- Chip cover with ceiling

For safety, door is interlocked to hold machine movement when they are not closed.

 Machine control panel installed on shop floor Two electrical sockets with capacity of 5 ampere in 100 volt and one socket for RS-232-C port are provided on it.

# **Optional accessories**

Primary power to the machine will be shut-down automatically after power to CNC has been OFF when M02 or M30 in a program has been executed while the

switch "AUTO POWER OFF" had set at "ON"

☆2. Work light

Water proof type 40W fluorescent lamp is mounted under crossrail

☆3 Operator call lamp

3-color lamp is mounted on top of right column. Green lamp show the machine is running under automatic mode.

Yellow lamp show one of M00, M01, M02, N30 and M52 is executed to wait for operator's assistance

show the machine is stopping in some

#### 4. Automatic tool changer (ATC)

Tool storage capacity 90 120 tools Maximum milling tool size When same size tool are in adjacent pots.  $\phi$ 125 mm Adjacent pots are empty φ240 mm Maximum turning tool size

Adjacent pots must be empty □ 160 mm Maximum length of tool 400 mm Maximum mass of tool Maximum moment around gauge line

53 N-m (.5.4 kgf-m) Tool selection Pot address random short way

· Turning tool is recommended to be stored in pot with numbers of multiple of 5. An interlock is provided in the controller based on a kind of tool for turning or milling by judging these tool numbers.

· A dummy tool for protecting spindle taper should be

#### 5. Tool breakage detection device for small drill or tap

The machine will check length of the tool twice, before loading it on the spindle and after removed it from the spindle, to find tool breakage by comparing these two data, when T80xxx is programmed for tool number.

6. Pull stud

Type MAS P50T-1 (30°)

#### 7. Automatic pallet changer (APC)

2 600 mm Maximum swing of workpiece · Maximum swing of workpiece on next pallet 2 400 mm · Distance between door gates 2 600 mm · Number of pallet 2 pallets 7 000 kg · Rotational speed at set-up station 1.0 min

8. External program number search function The new program number (8 digits) will be searched automatically to start machining, when new pallet has been loaded on the machine

#### 9. Automatic attachment changer (AAC) Attachment will be mounted on the ram automatically through program.

Number of attachment to be stored

10.Attachment indexing at every 5 degree or every 1 degree (AAI)

There are two ways for program as bellow · Automatic indexing at every 5 degree or every 1 degree

· When selected three dimensional coordinate conversion

## 11. Several kinds of attachment and its

Please refer to page 16 and 17 in this catalogue in detail

#### 12.4-axis head with AATC feature

64/53 4Kw · Spindle power · Spindle torque 236 N·m[174.6Ft-lbs] Spindle speed 150~12 000 min

 Spindle swivel range ±95 degree B: 10 800 deg/min(30min<sup>-1</sup>) Rapid swiveling B: 10 800 deg/min(30min<sup>-1</sup>

 Indexing accuracy R: +5 sec B: ±3 sec Repeatability Feedback scale Rotary scale

Simultaneous 5 axes control

because of wiring to it.

Available NOTE Primary power capacity must be 170 KVA. AAI to the ram is not available for this unit, 13. Power chip conveyor (type B) Two sets of hinged type co longitudinal along both side of bed.

#### 14 Coolant unit B

Foundation floor for the unit should be 300 mm below the machine foundation floor.

Additional short hinged type conveyor is integrated in the unit.

· Coolant tank capacity 800 Liter

· Effective volume of coolant on the unit 440 Liter

· Coolant pressure at pump delivery port Coolant Water base to prevent accident of fire Coolant will be delivered from nozzles mounted on the attachment when M08 is programmed.

#### 15.Chip bucket

This is a portable type bucket to be utilized together with above item 15.

The bucket could be swing for discharging chips from it

#### 16.Air blow device

Air can be exhausted from the same nozzle and/or spindle center as coolant.

Air compressor Air volume depends on compressor capacity

17. Air blow through spindle center function This is available on standard snout.

Please refer to other attachment in detail.

#### 18.Mist coolant unit

Coolant will be exhausted in mist through the same nozzle as coolant when programmed M07.

#### 19 Automatic measuring device

ON/OFF of the device will be controlled by M codes. This device consists of radio touch probe manufactured by Renishaw and one set of standard software (including software for checking bore and step) generated by Shibaura Machine. Printer is not included in the system Radio frequency to be used on the radio probe is 2.4

Skip function in CNC optional specification must be selected when choosing this device.

NOTE : Same type of radio touch probe is used on a existing machine near-by the machine. Please let us know, because a radio frequency must be adjusted prior to machine shipment

# 20. Automatic tool length measuring device

software A reference tool is not included, but is able to be

supplied from Shibaura Machine when ordered. Skip function in CNC optional specification must be selected when choosing this device.

#### 21.Ball screw cooling through core

Ball screws to be applied on feed system on linear axes of X, Y, and Z. are cooled through center core for better positioning accuracy.

#### 22. Free arm pendant

The pole of arm pendant will stand on shop floor. Operator stand will be deleted when this is selected.

#### 23 Pre-heat timer

There are two type of pre-heat timer as follow. Type A: Power to the machine including CNC and hydraulic unit will be turned ON at

pre-determined time by a timer Type B: In addition to function in type A special machine will start automatically with the special warming-up program

#### 24. Unit to different power specification

Independent transformer will be supplied. Please inform us your power specification when

25. Heat expansion compensation on Z axis

Special function in CNC optional specification must be selected when choosing this. This is exclusively developed for "Die manufacturer" by

26. High pressure coolant

sure at pump delivery port

Shibaura Machine to minimize expansion on the ram in order to achieve fine surface in contouring.

2.0 MPa

#### 27.Full CNC control on W axis

Special hydraulic servo balance system is applied on the W axis.

- 3 000mm/mir
- Feedrate  $1 \sim 3.000 \text{mm/min}$ W axis is parallel axis of Z axis and could be combined
- with another axis except Z axis. · Tool could change automatically through ATC at
- higher position than 250 mm. Hydraulic pump motor will be 15 kW and size of the unit will be larger than standard case, because tank capacity will be 300 Liter in stead of 160 Liter on

#### 28. Feedback scale on W axis

29.Extra step positions on W axis

Number of steps are 11 position and pitch is 100 mm.

11 kW

#### 31.Air compressor

A screw type compressor will be supplied with 11 kW

Independent power line to the unit must be prepared by

#### 32. Customer's machine color

Sample piece painted with the custom color must be supplied from the customer in addition to Munsel specification of the color. Paining color on such unit as pendant, company mark, purchased unit are always standard color of manufac-

33. Exchange of axis name between X and Y This exchange can not be applied on the case when

#### 34. Coolant through tool block

This is available only for milling attachment.

Turning tool holder will interfere with this block and this block is not furnished when a turning holder is selected. Coolant will be delivered through this block when tool with coolant through tool feature is mounted on the

#### 35. Tool holders

(19) Side lock holder

more to page in in deta		
(1) Square tool holder	□32W160L230	S-3M910
(2) Boring tool holder BFP	□25D110L250	S-9K746 #1
(3) Boring tool holder BFP	□25D110L300	S-9K746 #2
(4) Boring tool holder BFP	□25D110L350	S-9K746 #3
(5) Boring tool holder BFP	□20D80L200	S-9K747 #1
(6) Boring tool holder BFP	□20D80L250	S-9K747 #2
(7) Boring tool holder BFP	□20D80L300	S-9K747 #3
(8) Boring tool holder BFP	□20D80L350	S-9K747 #4
(9) Boring tool holder BA	□20D110L250	S-9K748 #1

(12) Boring tool holder BA □20D80L200 S-9K749 #1

(13) Boring tool holder BA 20D80L250 S-9K749 #2 (14) Boring tool holder BA □20D80L300 S-9K749 #3 (15) Side lock holder φ25D65L150 S-9K750 #1

(16) Side lock holder φ32D72L180 S-9K750 #2 (17) Side lock holder φ40D80L200 S-9K750 #3 (18) Side lock holder φ50D90L250 S-9K750 #4

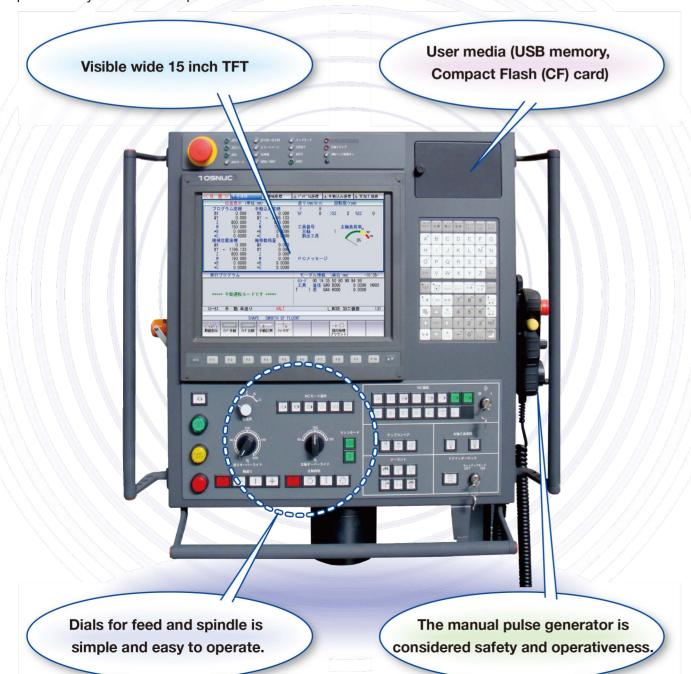
(20) Side lock holder φ68D110L200 S-9K751 #2 Explanation on code of holder: 20D110L350

φ63D98L200 S-9K751 #1

# TOSNUC PX100 STATE OF THE ART CNC CONTROLLER DEVELOPED TO MAXIMIZE MACHINE PERFORMANCE & PROFITS.

# TOSNUC PXIOO

TOSNUC PX100, A personal computer architecture. Integrated into our TOSNUC controller developed specifically to enhance our CNC controller with higher performance functions and even nore versatility. Our goal to create more innovative features that support easier operation thus contributing to an increase in productivity and machine performance.



# Versatility in operation based on our vast experience

Based on our extensive experience integration between mechanical and electronic technology. Our new CNC controller was developed with an emphasis on easy operation, easy to understand and easy to remember. This perfect combination is the Key to achieving higher machining accuracy in high speed machining.

#### Pop-up menu

By pressing a soft key on the selected screen a menu will appear showing the desired function on a sub display window.

Multi screen

background edit

The screen can be divided

DATA compensation

upon machining.

and during editing

into three sections to display

two program screens and the third shown MODAL OFFSET

information which is required

menu type system avoids complicated hierarchy in software and shortening the scan time to process a desired function

These three screens run independently during automatic operation

A new program can be generated and created utilizing a clipboard

feature and or background split screen edit two programs

## File editing screen

Multi-task and multi-window is a feature that enables you to open a window file from any current screen to perform program input/output deleting or copy

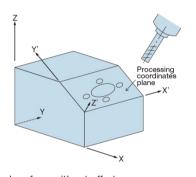
programs from a user media.

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a program to execute a calculator screen clipboard. Program list and memory are connected to a user media and displayed on the screen allowing the program to be checked in a preview window within the same screen during input or output of

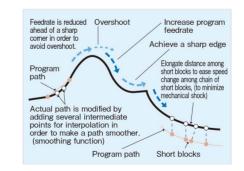
#### **Program support functions**

A general program running on G17 plane when programmed on X-Y plane and machining a depth on inclined surface as shown does not require a program modification. This very important feature convenient and executable with G command and canned cycle simplify machining of an inclined surface without effort.



simultaneously as compared to a personal computer.

# Advanced functions for high speed machining and higher machining accuracy



**Preview control** 

Generally a profile that is being machined will require a true

shape. Shape error decreases as servo gain increases.

However a high servo gain causes overshoot and increases

Acceleration to the mechanical components or system which in turn causes a bad surface finish during machining.

Preview or SHAPE CONTROL is based on the optimum control

This important development prevents such an effect on

countoured surfaces and minimizes shape error without the

theory developed specifically to prevent such an outcome.

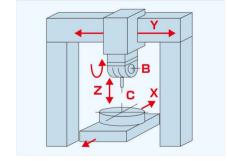
machine vibration causes from large.

need for a high gain servo system

### Tool contact point control

Program path must be the path of tool and program path.

This important feature is key in preventing tool path error due to change of tool position on rotary axis.



#### Tool nose position compensation

This will compensate several errors and offset on mechanical construction. In the case of MP-2620(U), there could be

errors in followings. ·Inclination of C axis center line to X axis

- ·Inclination of C axis center line to Y axis
- Inclination of B axis center line to X axis
- ·Inclination of B axis center line to Z axis
- ·Offset between B axis center and spindle center in X axis direction

position changes during rotary axis motion. Actual compensated command of each axis is calculated out from tool and nachine data

### **CNC** specifications TOSNUC PX100



## Basic and pack specifications

Items with mark "☆" are pack specifications.

#### A. Controlled axes

☆Number of controlled axes

5 axes : (X, Y, Z, W, and C)

Word address format

G90/G91

6 axes: when optional B axis is selected.

Number of simultaneously controlled axes

Positioning (G00) and linear interpolation (G01)

Simultaneously controlled 4 axes X, Y, Z, C

Simultaneously controlled 5 axes X, Y, Z, C, B when B axis head is furnished.

Circular interpolation (G02 and G03)

X-Y, Y-Z (W), Z (W)-X Simultaneously contorolled 2 axes

☆Synchronous feed control

#### B. Input command

Linear axis 0.001 mm 0.0001 degree Rotating axis

Maximum programmable dimension

Linear axis	±99999.999 mm
Rotating axis	±9999.9999 degree
Data code	Automatic recognition of ISO/EIA code
	JIS B6311 ISO 6983/1
	EIA RS-358-B EIA RS-244-E
Data format	Variable block with decimal point

Absolute/incremental programming

Decimal point input

#### C. Interpolation functions

Positioning G00 G01 Linear interpolation G02 (CW), G03 (CCW) Circular interpolation

#### D. Feed functions

Rapid traverse refer to machine specifications Feedrate F5 direct programming in mm/min Dwell G04 and program code of F"or P" maximum dwell time is 999.99 seconds

Manual jog feed

Move the machine continuously in a feed or rapid selected

Rapid traverse override

in a range of 0 ~ 100 % in 10% increments

Feedrate override

in a range of 0 ~ 200 % in 10% increments

Automatic acceleration/deceleration

Linear type acc./dec. in feed, rapid and jog feed

S-shape acceleration/deceleration for rapid

☆Threading

G33, In-feed is synchronized with spindle rotation.

☆Feed per minute/ Feed per revolution	G94/G95
☆Dwell per revolution	G05

☆Hand wheel feed (portable type

0.001 mm, 0.01 mm, 0.1 mm/div. Linear axis Rotating axis 0.0001 degree, 0.001 degree, 0.01 degree/div.

☆Random start angle threading

Start angle of thread can be specified for multi-start thread.

#### E. Program memory and editing

☆Part program storage

600 m equivalent length of punched tape or 258 kB 512 program can be registered.

100~200m will be occupied by the manufacturer.

Part program edit (in back ground)

Stored programs can be edited about various data.

Program deletion, program copy, Program number change, search, jump, operation cancel, a range designation and deletion, a range designation and copy, replace, program insert, etc.

Program name

8 digit character following \$ or O.

Program comment in () can be 38 characters.

Sequence number	N5
-----------------	----

Sequence number search

Search a block bearing the specified sequence number in forward and backward and and stop at the block

Program nesting list

A list of program nesting status will be displayed on a screen

Program offset list

Following list will be displayed on a screen.

Fixture offset list

B code list

Program format check

#### F. Operation and display

☆Operation panel

Customized kevs

Tool file

Display function

Screen clear function

Mode selection

S, F manual setting

S, F automatic setting

Spindle motor load indication

Working time indication

Counting lot number

Calendar timer

Machining record

Register user name Memory operation

MDI operation

#### G. Input and output functions and devices

RS-232-C I/F port A

A part program, offset data, etc. can be loaded and dumped through this port.

☆User media

A part program, offset data, etc. stored on USB memory and/or compact flash card can be loaded and dumped through this

#### H. S. T. M function

Spindle (S) function 5 digits following word "S" 50~150% in 10 % increment Spindle speed override Tool (T) function 6 digits following word "T" Miscellaneous (M) function 4 digits following word "M"

#### I. Tool offset

Tool length offset

Tool offset G45, G46, G47, G48 G40, G41, G42 Cutter compensation C ☆Expansion of number of tool offset Tool length offset 899 sets including standard

Tool diameter compensation

#### J. Coordinate system

Coordinate system setting G92 G53, G57 ☆Fixture offset 99 sets of data are available.

Fixture offset 2 G54, G55, G56 Return to 2<sup>nd</sup>, 3<sup>rd</sup>, or 4<sup>th</sup> reference point G21

#### K. Operation support function

Control IN/OUT

Single block

Optional stop

☆Optional block skip

Dry run

Machine lock

Auxiliary function lock

Z axis feed cancel

Manual absolute ON/OFF

Override cancel

All clear Reset

Feed hold

Cycle stop

Re-start

Sequence number collation and stop

Data input through keyboard in manual mode

Single block control

Feed hold control

Override control

Hand wheel interruption control

Manual interruption

Hand wheel interruption

Tool length/diameter measurement in manual mode

#### L. Programming support function

Plane selection

Radius programming in circular interpolation

Positioning on machine coordinate system

Sub program call

G43, G44, G49

899 sets including standard

Random angle chamfering and corner R

Canned cycle

Automatic corner override

☆Programmable mirror image

☆Plane conversion

☆Pattern cycle

☆Coordinate conversion

☆Macro programming

☆Three dimensional coordinate conversion

☆Spindle angular control

#### M. Compensation function for mechanical accuracy

Backlash compensation

Pitch error compensation

Uni-directional positioning

☆Pitch error gradient compensation ☆Straightness compensation

#### N. Machine support function

Feed interlock

☆External deceleration

O. Turning function

Threading

Retract in threading

Continuous threading function

Variable lead threading

Feed per revolution/Feed per minute

13

15

Diameter programming	
Direct dimension programming on drawing	
Chamfering/corner R	
Standard turning canned cycle	
Compound turning canned cycle	
Direct input of coordinate shift data	
Constant surface speed control	
Tool offset	
Nose R compensation	
Tool geometry/wear compensation	
Counter input of offset data	
Direct input of measured data for tool offset	
Actual spindle speed indication in T code	
Chamfering ON/OFF	
Dynamic change of programming between radius and diam	eter
P. Safety and maintenance	
Emergency stop	
Overtravel check	
Stored stroke check	
Axis interference check II	
Self-diagnosis	
☆Axis interference check I	
☆Door interlock	
Q. Panel and room condition	
Q. Panel and room condition  Power specifications	
Power specifications	
Power specifications Room conditions	

Optional specifications	
A. Controlled axes	
1 Additional controlled axis	B axis for optional 4-axis head automatically selected with the head
B. Input command	
2 Inch/metric selection	G70/G71
C. Interpolation functions	
3 Helical interpolation	G02/G03
4 Hypothetical axis interpolation $\alpha$ is an axis address. The atthis program.	n G07 $\alpha$ 0/1 axis specified for $\alpha$ will never move in
5 Cylindrical interpolation	G67 for machining cylindrical cam
6 Involute interpolation	G105

	G102/G103
8 Spindle normal direction control	G140/G141/G142
D. Feed functions	
-	G843/G844/G845 e speed is 20 $\sim$ 750 min <sup>-1</sup> .
10 Synchronous threading For threading on large diameter by boring to	tool
E. Program memory and editing	
Storage capacity C 5 400 m, Storage capacity D 7 800 m, Storage capacity E 10 200 m,	538 kB, 1 024 programs 1.25 MB, 1 024 programs 2.2 MB, 1 024 programs 3.15 MB, 1 536 programs 3.95 MB, 1 536 programs ecification when selected.
12 Compact flash memory (CF)	2 GB
F. Operation and display	
13 Display on the screen	in English
G. Input and output functions and devices	
14 Remote buffer operation Pro	otocol A (handshake type)
Protocol	B (DC control code type)
15 Binary operation	Binary data
16 High-speed LAN linkage Host Protocol	FTP server
Connecting cable NOTE	10 base-T
Following are customer's responsibility 1, Installation and set-up of LAN network 2, Connecting cable and connection to the Select one of the High-speed LAN lin memory (CF) above.	
H. S, T, M function	
I. Tool compensation	
17 Tool wear compensation memory	
18 Three dimensional tool compensation	G30/G31
19 Tool length offset in tool axial direction G	3143/G149 for 4-axis head
J. Coordinate	
K. Operation support function	
20 Hand wheel feed in tool axial direction	for 4-axis head
21 Foreground plotting Tool path of current program on vertical displayed on the screen.	dinate for machining
22 Manual centering function Check a workpiece and set a coor	rogram
22 Manual centering function	rogram
22 Manual centering function Check a workpiece and set a coor automatically with help of special macro pi	ation in MDI and manual

25 Fixture offset data input

26 Scaling

27 Figure copy	G721/G72
28 Circle cutting by compensation	on Radius is adjusted in circle cutting
29 Estimation of machining time	e and NC plotting function
30 Pattern cycle conversion to A short program of pattern constructed with many block	cycle is converted to popular program
•	ing area is specified to shift Z axis i dify shape of it without changing bas
M. Compensation function for	mechanical accuracy
32 Thermal expansion compens	sation on Z axis
N. Machine support function	
O. Automation support function	n
33 Skip function	G61 for several measuring function
34 Tool breakage/wear detection	n
35 Counting tool working time.	
36 Spare tool selection A spare tool will be selected trouble as life, breakage, wea	d automatically when a tool had suc
,	
37 Retract function	At the time of tool breakag
37 Retract function 38 Program check and creation	next operation will be checked an
37 Retract function 38 Program check and creation Format in the program for prepare a tool list in it while a 39 Interruptive macro	of slated tool next operation will be checked an current program is working.
37 Retract function 38 Program check and creation Format in the program for prepare a tool list in it while a 39 Interruptive macro A macro program is activa	of slated tool next operation will be checked an current program is working.  tted by a external signal o interru
37 Retract function 38 Program check and creation Format in the program for prepare a tool list in it while a 39 Interruptive macro A macro program is activa machine movement.	of slated tool next operation will be checked an current program is working.  Ited by a external signal o interru

#### 42 NRBS interpolation

R. Others	
43 Tool tip position control	for optional 4-axis head

44 Assembly error compensation on 5 axis head for optional 4-axis head

45 Thermal expansion compensation on 5 axis head

for optional 4-axis head

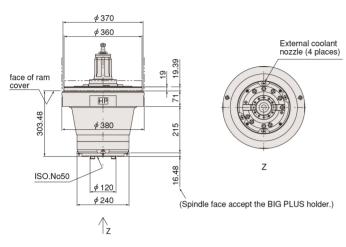
G158

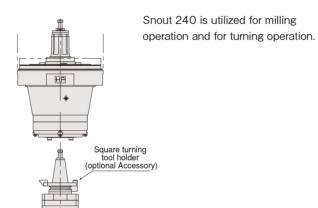
G64/G65

## **Various kind of Attachments**

### Standard accessory

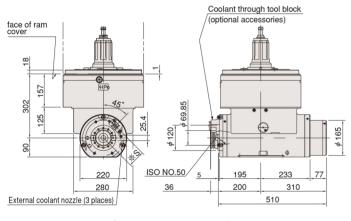
### Snout 240





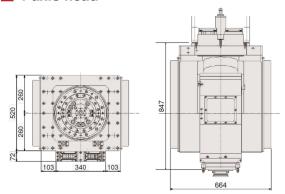
## **Optional attachment**

### 11 0.07N angle head

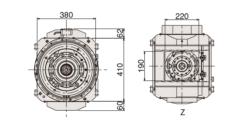


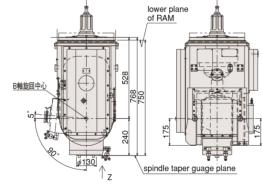
- maximum power: 100min<sup>-1</sup>/7kW
   maximum torque: 686N · m {70kgf · m}
   maximum speed: 5000min<sup>-1</sup>
   \*Size "S" becomes 80mm if there is no special mention in specifications

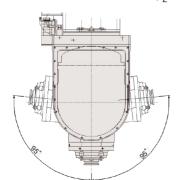
### 13 4-axis head



### 12 1 degree indexing head

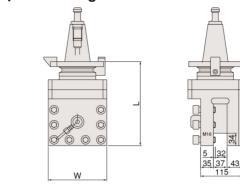






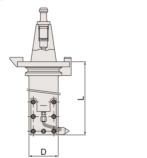
# **Turning Tool holders (optional accessory)**

### ■ Square turning tool holder



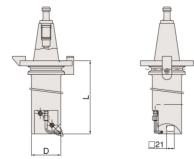
		(Unit mm)				
	Type	L W Mass (kg)				
(1)	S-3M910	230	160	30		

## **■** Boring holder BFP



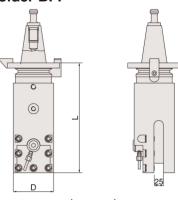
	(Unit mm)				
	Type	L	D	Mass (kg)	
(5)	S-9K747#1	200	80	12.4	
(6)	S-9K747#2	250	80	14.4	
(7)	S-9K747#3	300	80	16.4	
(8)	S-9K747#4	350	80	18.4	

### **■** Boring holder BA



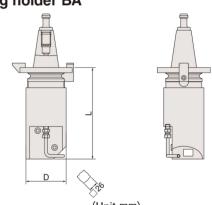
			(Unit mm	n)
	Type	L	D	Mass (kg)
(12)	S-9K749#1	200	80	12.9
(13)	S-9K749#2	250	80	14.9
(14)	S-9K749#3	300	80	16.9

### **■** Boring holder BFP



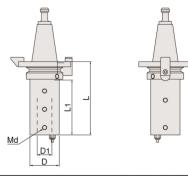
		(Unit mm)						
	Type L D Mass (kg)							
(2)	S-9K746#1	250	110	18.5				
(3)	S-9K746#2	300	110	22.5				
(4)	S-9K746#3	350	110	26.5				

# ■ Boring holder BA



		(Offic fillin)				
	Type	L	D	Mass (kg)		
(9)	S-9K748#1	250	110	18.5		
(10)	S-9K748#2	300	110	22.3		
(11)	S-9K748#3	350	110	25.9		

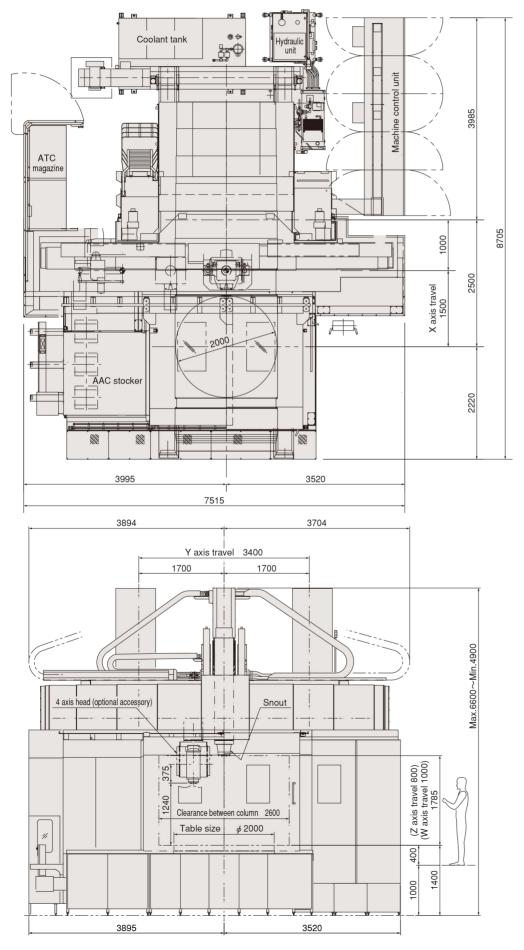
### Side lock holder



		(Ont min)					
	Type	L	L1	D	D1	Md	Mass (kg)
(15)	S-9K750#1	150	100	65	25	M10	8.8
(16)	S-9K750#2	180	130	72	32	M10	9.9
(17)	S-9K750#3	200	150	80	40	M12	11
(18)	S-9K750#4	250	200	90	50	M16	13.4
(19)	S-9K751#1	200	150	98	63	M16	11.6
(20)	S-9K751#2	200	150	110	68	M16	13.5

17

# **General view and Layout**



# Large and wider machining space

